



## Unboxing the UWB Linux Dev Kit for QM35825

00:00:04.820 --> 00:00:06.340 Welcome to our introduction

00:00:06.340 --> 00:00:09.760 to the Qorvo QM35825 Dev Kit for Linux.

00:00:10.300 --> 00:00:15.680
With Ultra-wideband high-precision ranging, this kit measures distance within 5 centimeters

00:00:15.680 --> 00:00:18.460 and is accurate to just 2 degrees between devices.

00:00:18.940 --> 00:00:20.400 And there's more.

00:00:20.400 --> 00:00:23.160
The kit also features
a built-in radar mode

00:00:23.160 --> 00:00:26.560 that scans the environment to detect motion and presence.

00:00:27.180 --> 00:00:30.480 Let's take a closer look at what's inside the box.

00:00:30.700 --> 00:00:34.080 You'll find a QR code card linking to the Qorvo dev kit page,

00:00:34.680 --> 00:00:39.020
a USB adapter
and two USB-C cables for power and control

00:00:39.500 --> 00:00:43.100 and your Qorvo evaluation boards, ready to use.

00:00:43.740 --> 00:00:45.700 The dev kit includes two modules

00:00:46.100 --> 00:00:50.000 each built around the same UWB radio board with four antennas.

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00:00:50.780 --> 00:00:55.020 Module one runs on a Raspberry Pi with Linux, perfect for onboard control.

00:00:55.520 --> 00:00:58.740 Module two connects to your PC via USB-C

00:00:59.040 --> 00:01:03.240 letting you control the radio directly using Python scripts and UWB Explorer app.

00:01:03.780 --> 00:01:08.160 It's a flexible setup, made for rapid prototyping and real-world testing.

00:01:09.180 --> 00:01:12.480 Start by installing the Qorvo UWB Explorer app.

00:01:13.100 --> 00:01:16.160
Then connect the kit using the USB-C cable

00:01:17.180 --> 00:01:19.000 and setup is complete.

00:01:19.680 --> 00:01:24.080 With just a few clicks, run distance measurements, explore angle detection

00:01:24.320 --> 00:01:27.920 and unlock radar-based presence sensing, all in one place.

00:01:28.940 --> 00:01:32.120 Visit our website at Qorvo.com for more information

00:01:32.120 --> 00:01:33.620 or to order your Qorvo Kit.

00:01:33.620 --> 00:01:35.260 Thank you for watching.